

## **Understanding Consistency Maintenance in Service Discovery Architectures during Communication Failure**

Chris Dabrowski, Kevin Mills, Jesse Elder

**WOSP 2002** 

Rome, Italy

July 25, 2002



## Dynamic discovery protocols in essence...

#### enable *distributed software components*

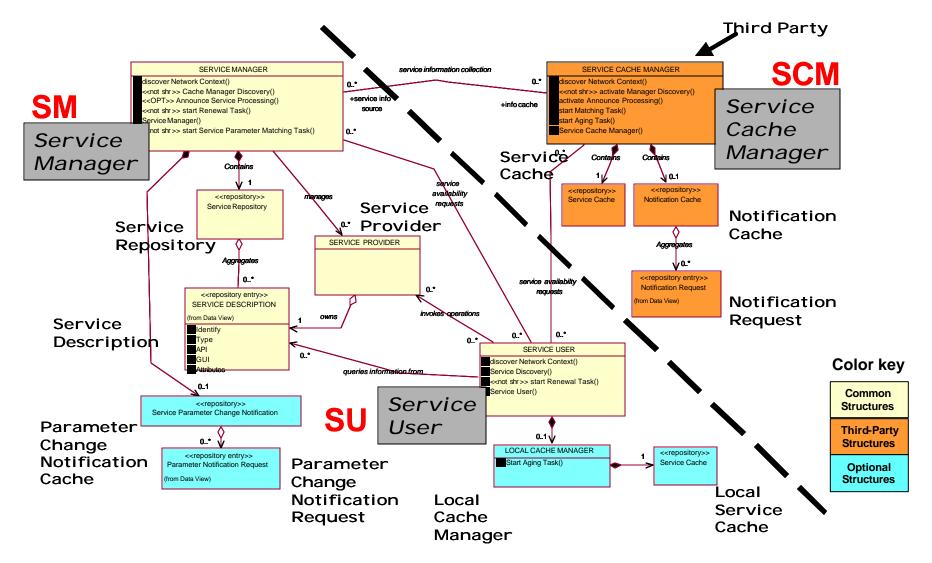
- (1) to *discover* each other without prior arrangement,
- (2) to express opportunities for collaboration,
- (3) to *compose* themselves into larger collections that cooperate to meet an application need, and
- (4) to **detect and adapt** to failures.

#### Some examples:



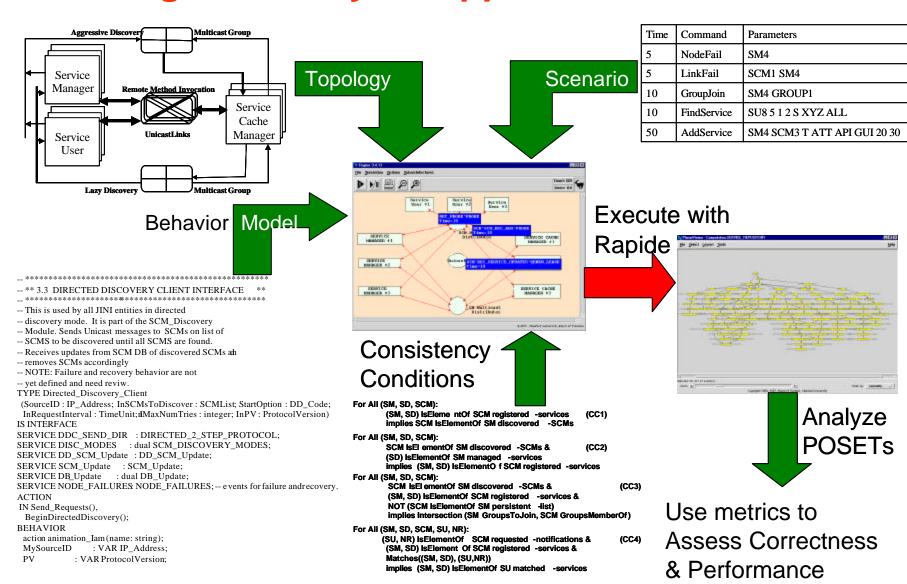


## **General Architecture for Service Discovery Systems**



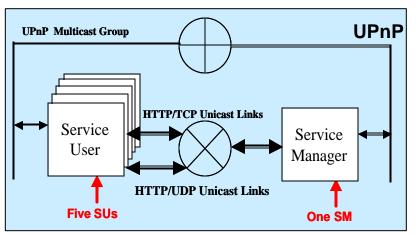


## **Modeling and Analysis Approach**



INFORMATION

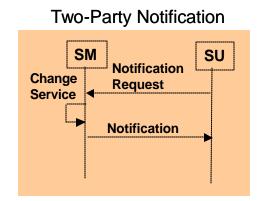
# How do various service discovery architectures, topologies, and consistency-maintenance mechanisms perform under deadline during communication failure?

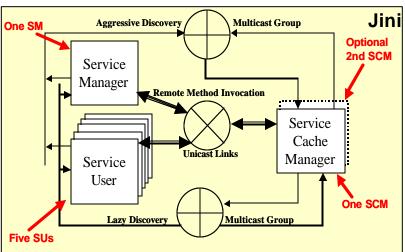


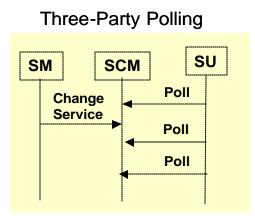
Two-Party Polling

SM SU

Change Poll
Poll
Poll







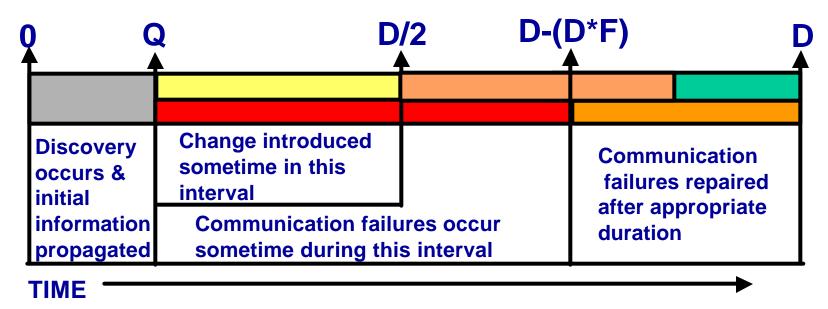
SM SCM SU

Change Service Notification Request Notification

**Three-Party Notification** 

INFORMATION TECHNOLOGY LABORATORY

## **Modeling Communication Failures**



#### Random Processes

- 1. Choose a time to introduce the change [uniform(Q, D/2)]
- 2. For each node, choose a time to introduce a communication failure [uniform(Q, D-(D\*F))]
- 3. When each failure occurs, choose a scope for the failure, where each of [Rx, Tx, Both] has an equal probability

Q = end of quiescent period (100 s in our experiment)

D = propagation deadline (5400 s in our experiment)

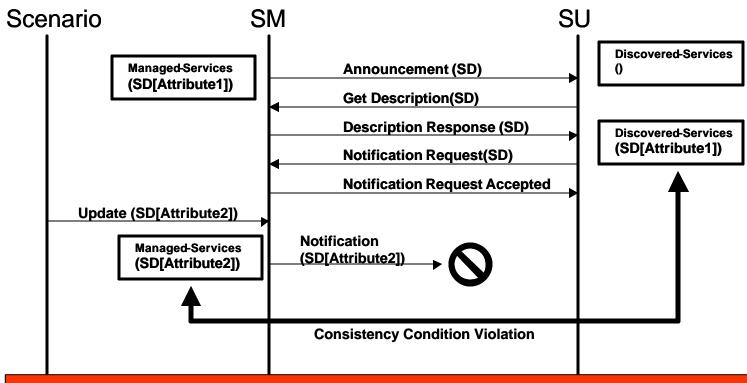
F = failure duration (variable from 0% - 75% in 5% increments in our experiment)



## **Monitoring Consistency**

For All (SM, SU, SD):

(SM, SD [Attributes1]) IsElementOf SU discovered-services
SD [Attributes2] IsElementOf SM managed-services
implies Attributes1 = Attributes2

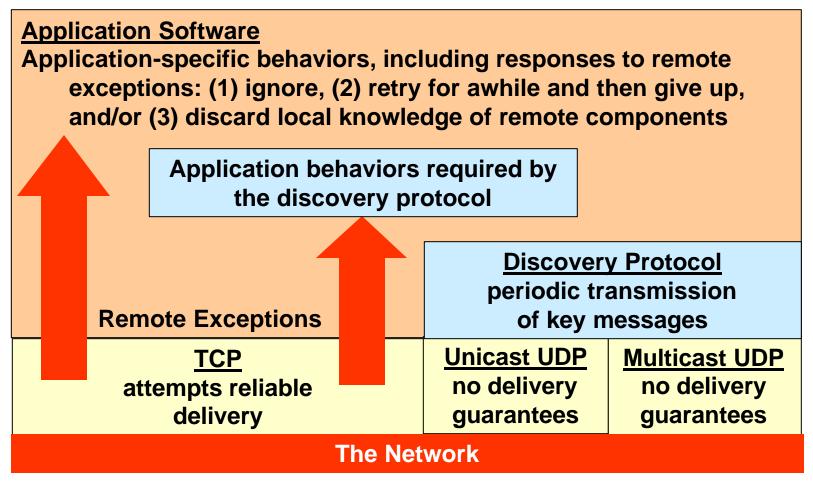


How well does the system restore consistency after restoration of communication?



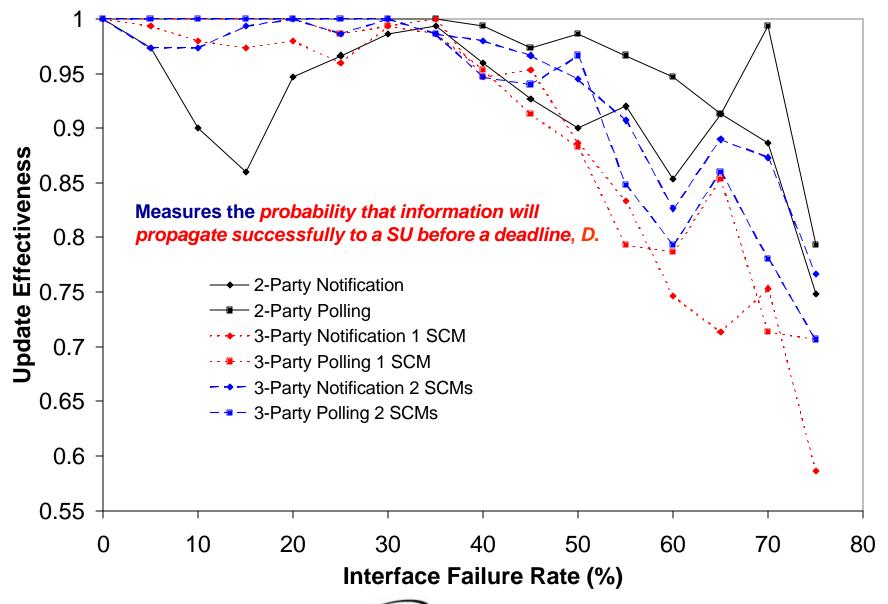
## Division of Failure Recovery Responsibilities:

Communication Protocol - Discovery Protocol - Application Software

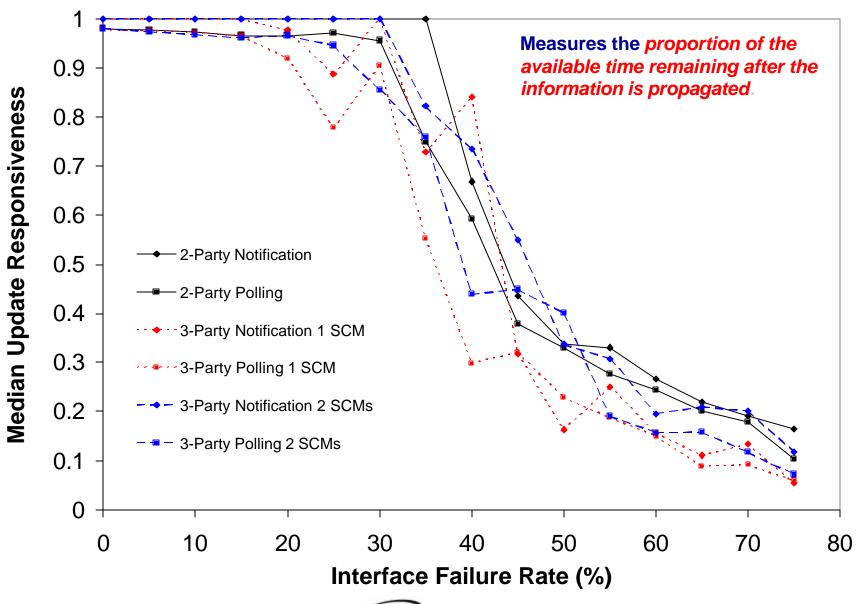




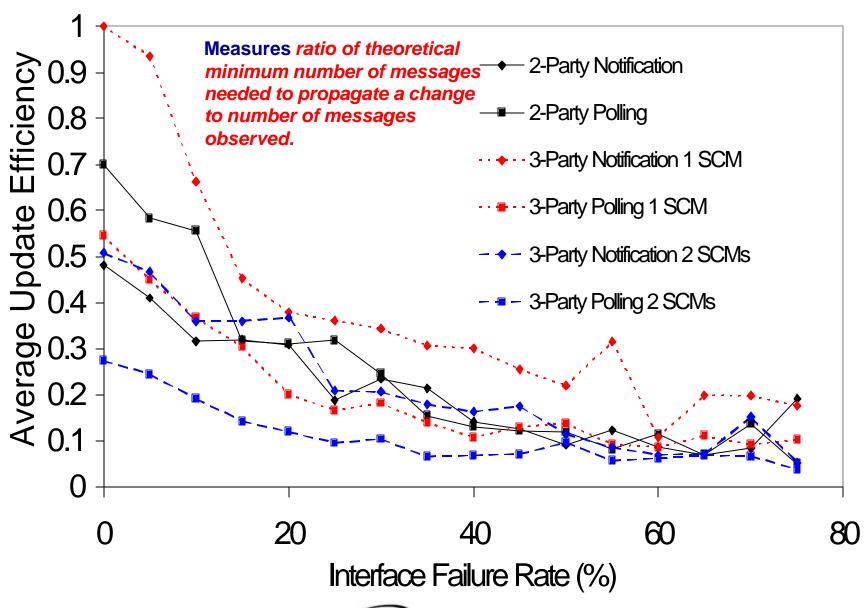
## Update Effectiveness UPnP (2-Party) vs. Jini (3-Party)



## Update Responsiveness UPnP (2-Party) vs. Jini (3-Party)



## Update Efficiency UPnP (2-Party) vs. Jini (3-Party)



#### **Conclusions**

- Executable architectural models represent essential complexity and reveal collective dynamics – leading to valuable insights
  - paper specifications do not represent dynamics very well
  - reference implementations exhibit substantial incidental complexity
- A single architectural model can be analyzed for behavioral, performance, and logical properties
  - limits errors and inconsistencies that can creep in when using multiple models to represent different facets of a design
- 2-party and 3-party discovery architectures share similar robustness properties during communication failure, but
  - sole reliance on TCP retransmissions to recover notifications leads to an unexpected saw-tooth in update effectiveness, which is most pronounced for UPnP (Jini includes some SM behaviors which compensate)
  - adding a redundant SCM in the 3-party architecture improves effectiveness and responsiveness nearly to the level of the 2-party architecture, but adding a redundant SCM also lowers efficiency

